

Leveraging Structures for Machine Reasoning

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Motivation

How can we combine deep learning and logic reasoning to leverage existing model biases?

Symbolic Execution

Interpretable

Extensible

Not Comp. Efficient

Neural + Symbolic

?

Neural Execution

Comp. Efficient

Data Hungry

Not Interpretable



Research Directions

More specifically we will look at:

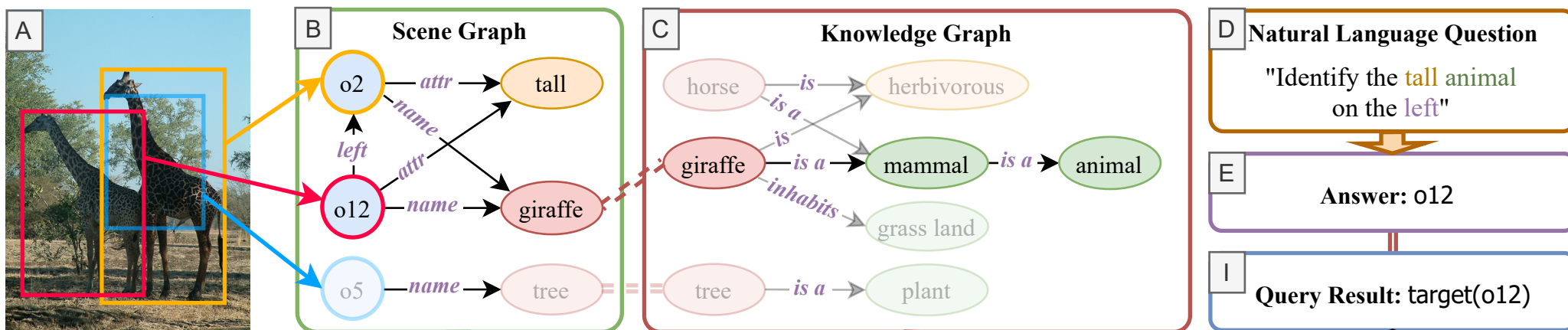
- **Image Question Answering**
 - **How do we run real world inference and training given symbolic representations?**
 - **Given natural inputs, can we quantify and leverage the uncertainty in their underlying symbolic representations?**
- **Rule learning and inference over videos**

Real world symbolic execution and training

(Mostly symbolic)

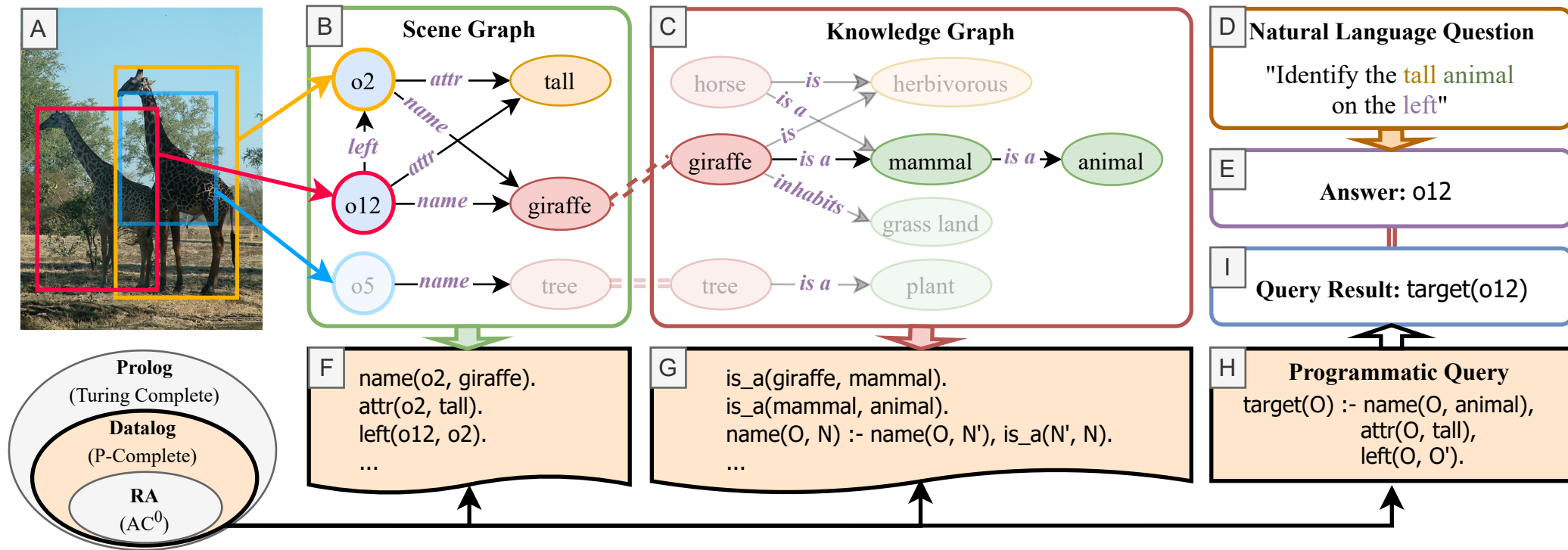
Real World Symbolic Execution - Example

Visual question answering with common sense.



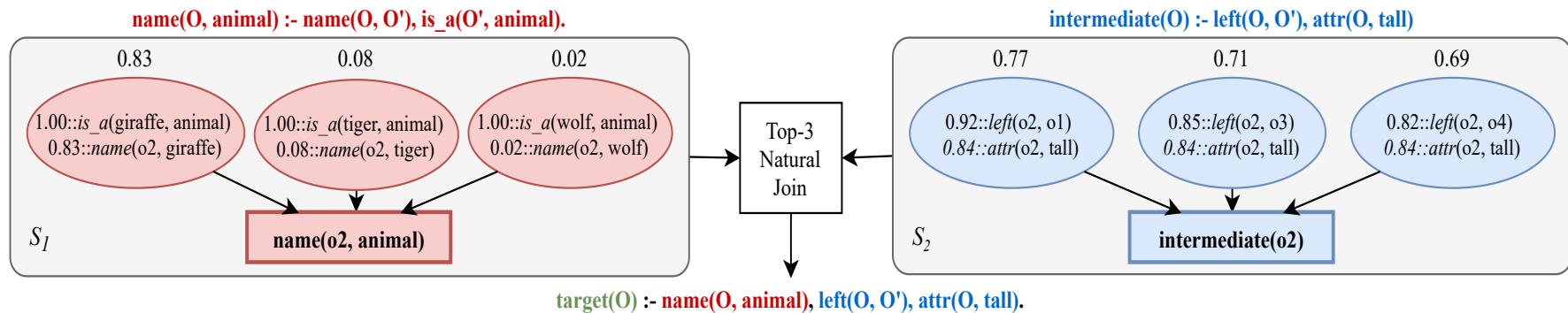
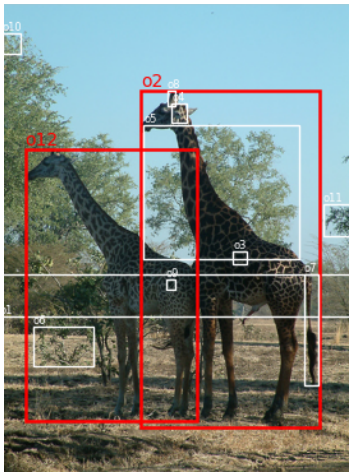
Real World Symbolic Execution - Example

Logical programming execution



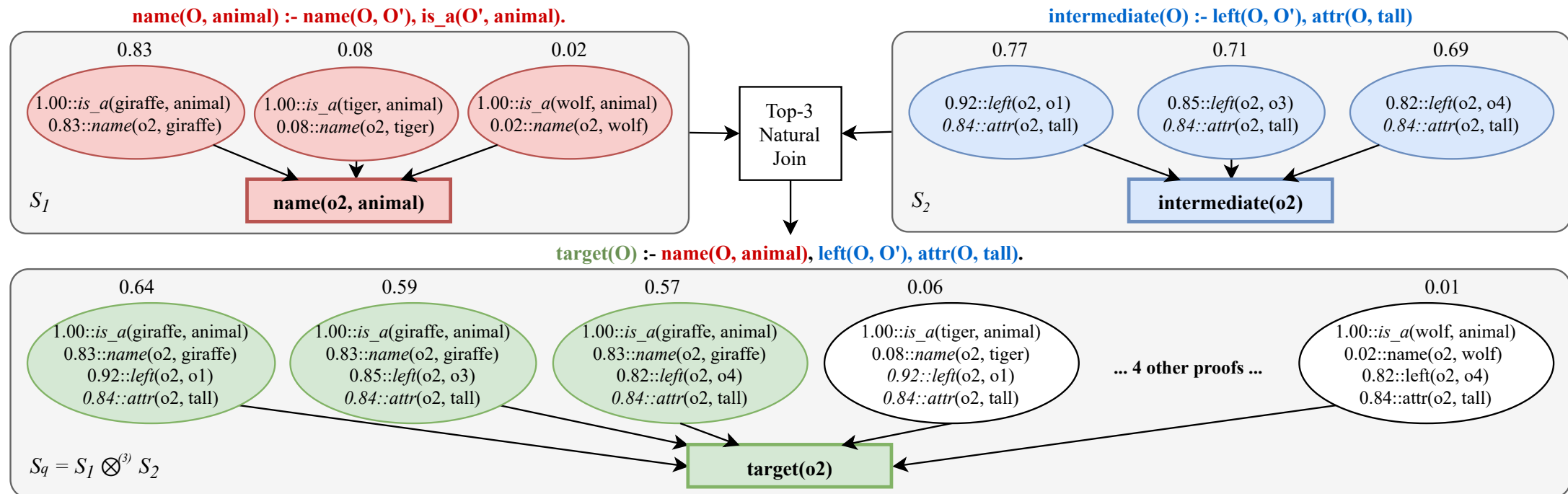
Real World Symbolic Execution - Issues

Probabilities for selecting an **object** conditioned on the **query** requires analyzing all possible combinations that satisfy the query.



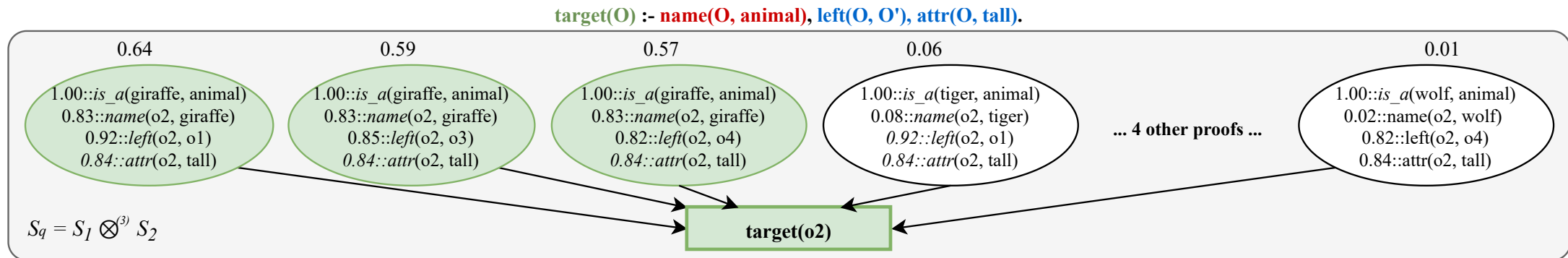
Real World Symbolic Execution - Issues

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Real World Symbolic Execution - Issues

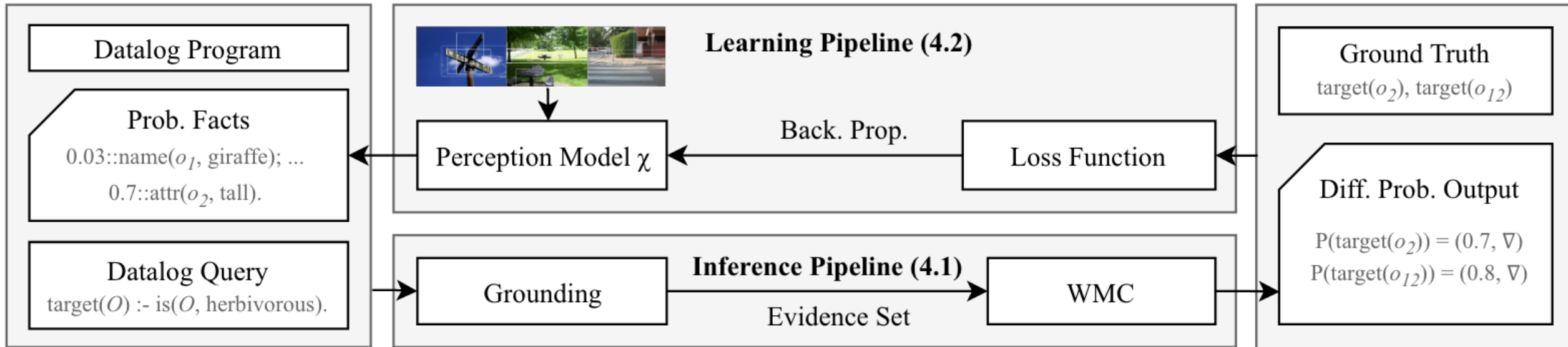
As the number of objects, knowledge, facts, and query length grows, this computation is exponential!



Intuition: take the **top-k** combinations at each step.

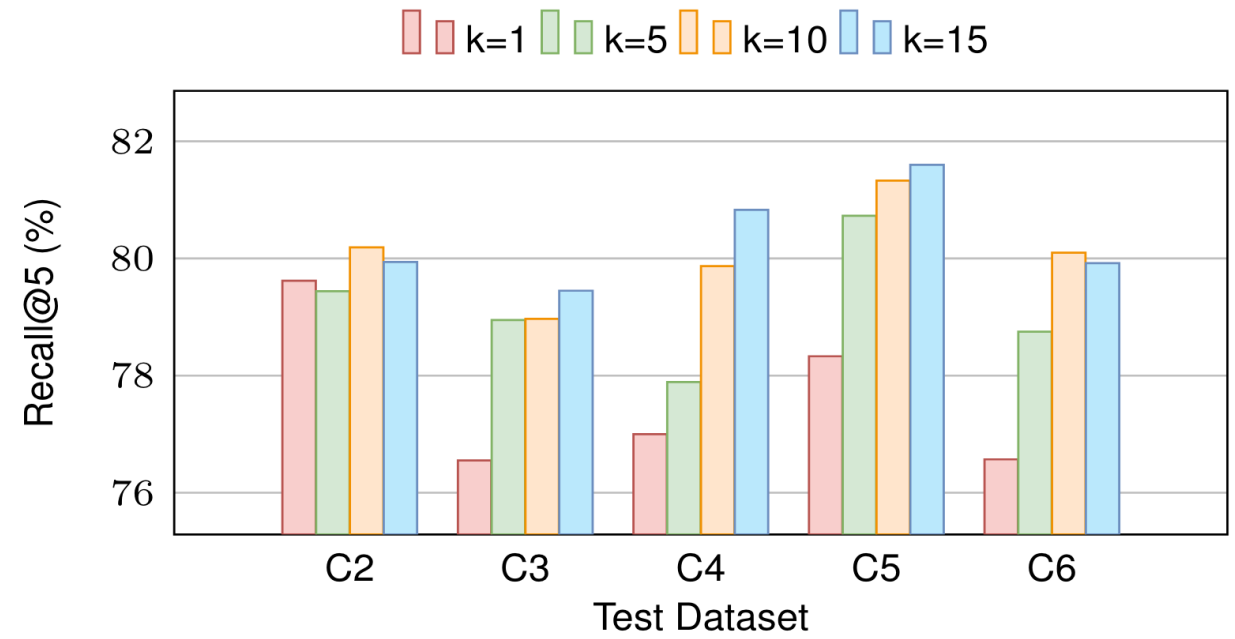
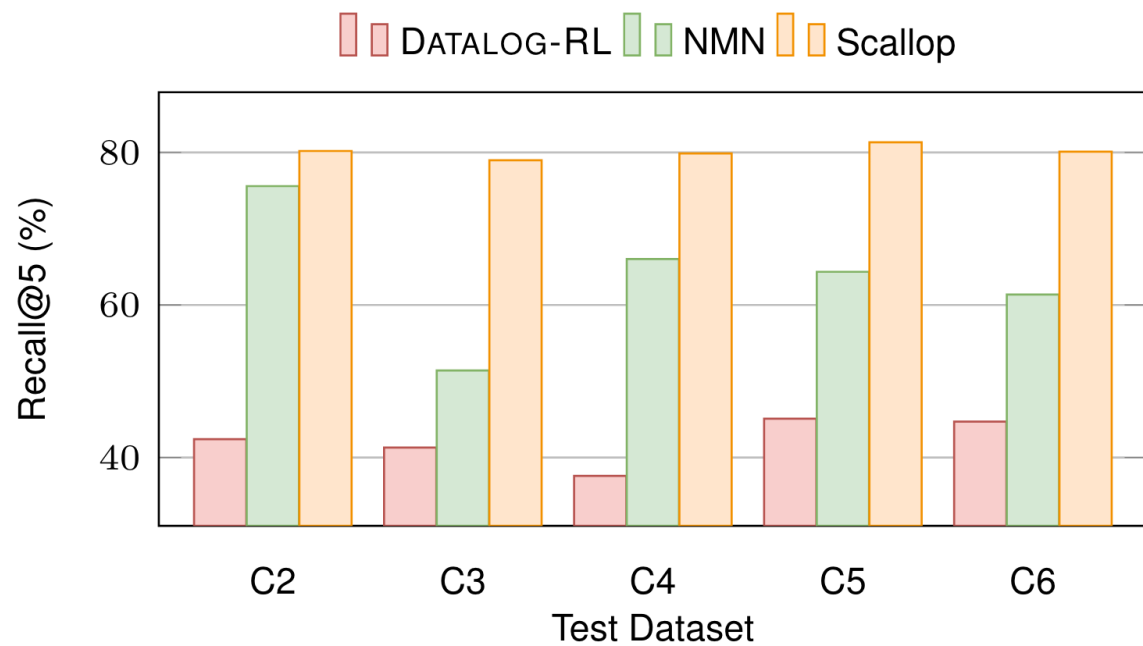
Real World Symbolic Execution - Scallop

Pass through gradients in addition to the combination probabilities to enable end-to-end training.



Scallop - Results

On a Dataset leveraging GQA and ConceptNet for the knowledge base.



Scallop – Future Work

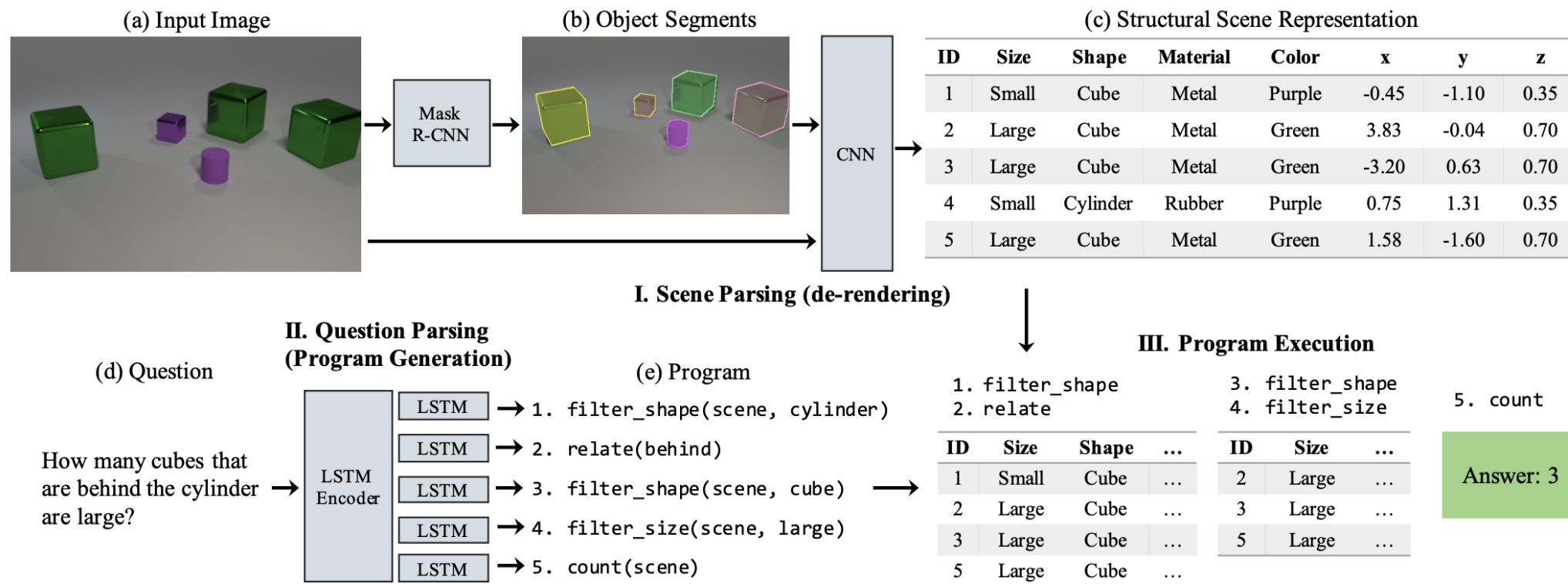
- **How to integrate natural queries?**
- **How does it scale to noisy knowledge bases?**
- **Can we better estimate the gradient?**

Recovering probabilistic symbolic representations from natural data

(A bit more neural)

Symbolic Execution - NS-VQA

Discretize the query as well as the objects.

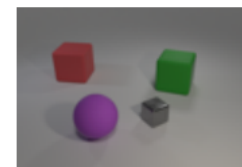


Symbolic Query

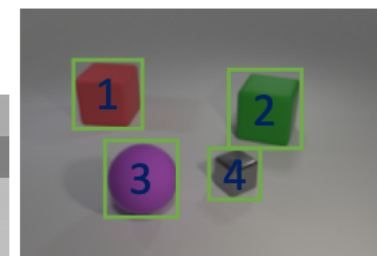
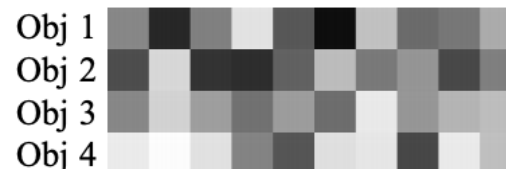
- NS-CL

Discretize the query but keep the uncertainty in the vision.

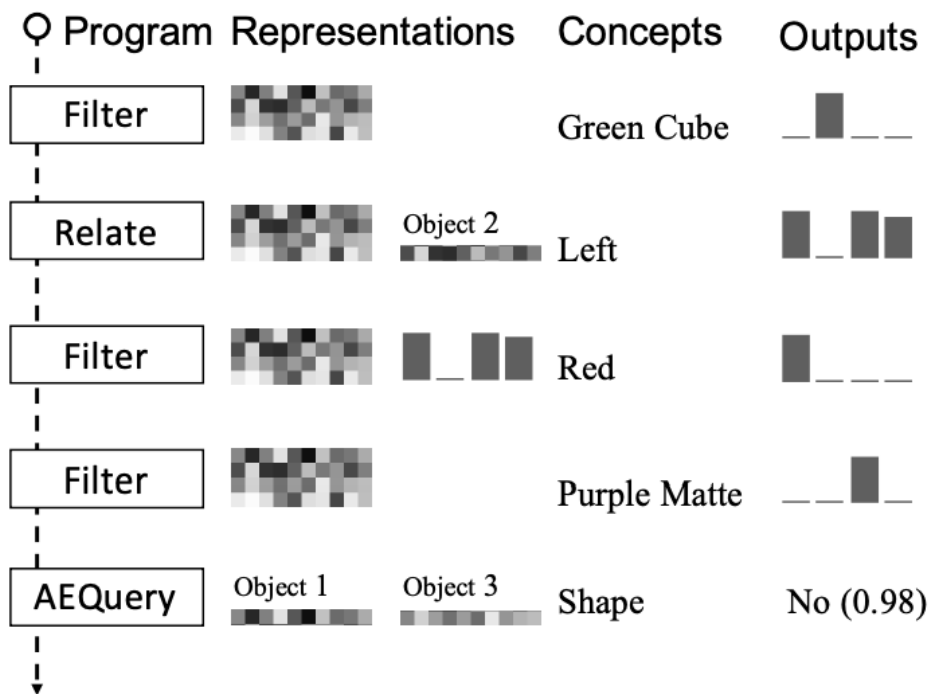
Q: Does the red object left of the green cube have the same shape as the purple matte thing?



Step1: Visual Parsing

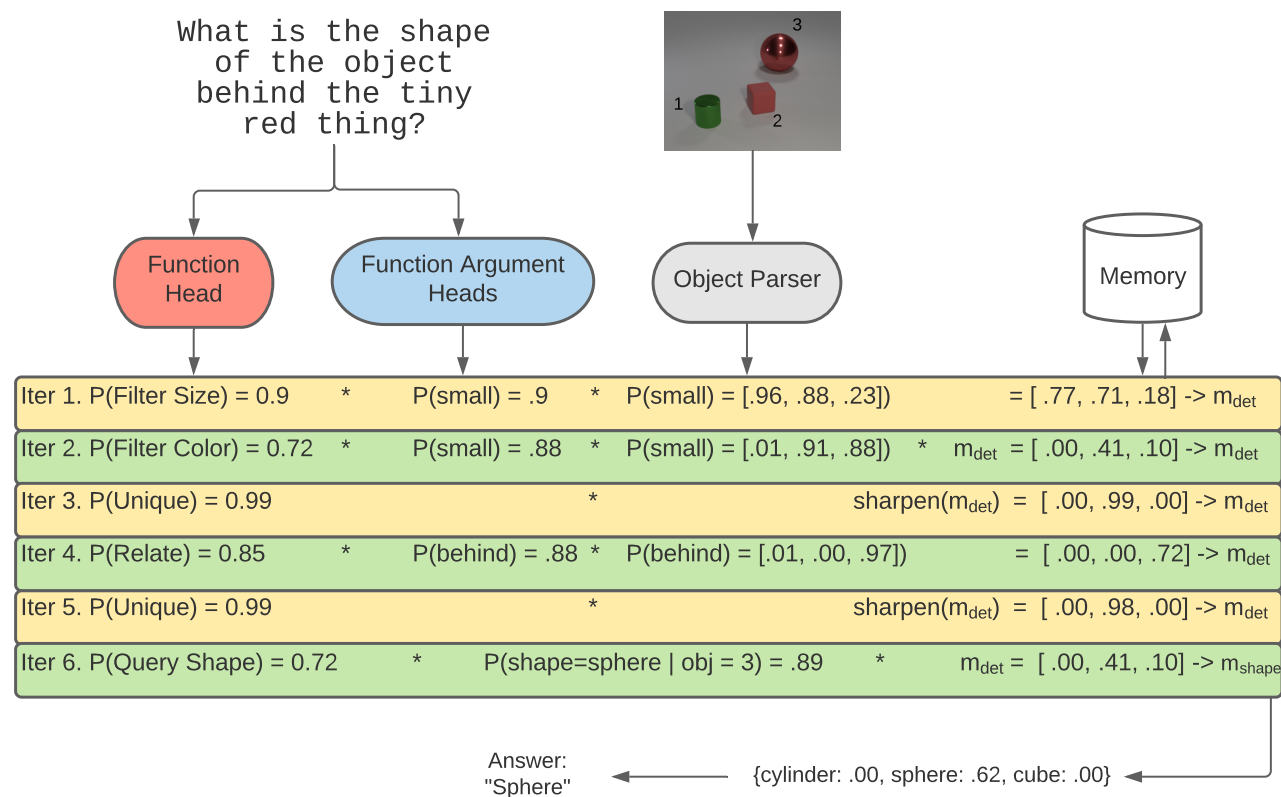


Step2, 3: Semantic Parsing and Program Execution



Prob. Query and Vision

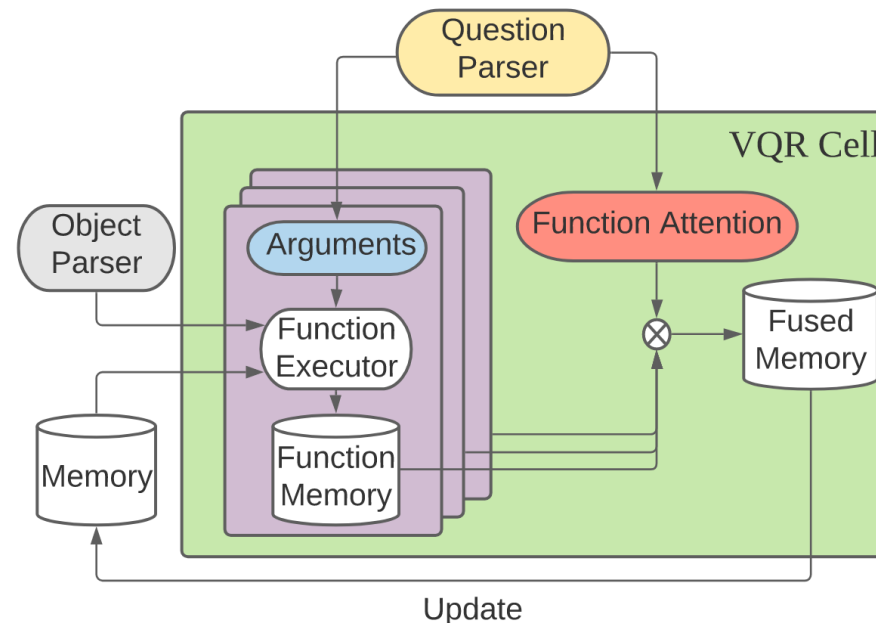
What if we carry the uncertainty for both the vision and the logical representations?



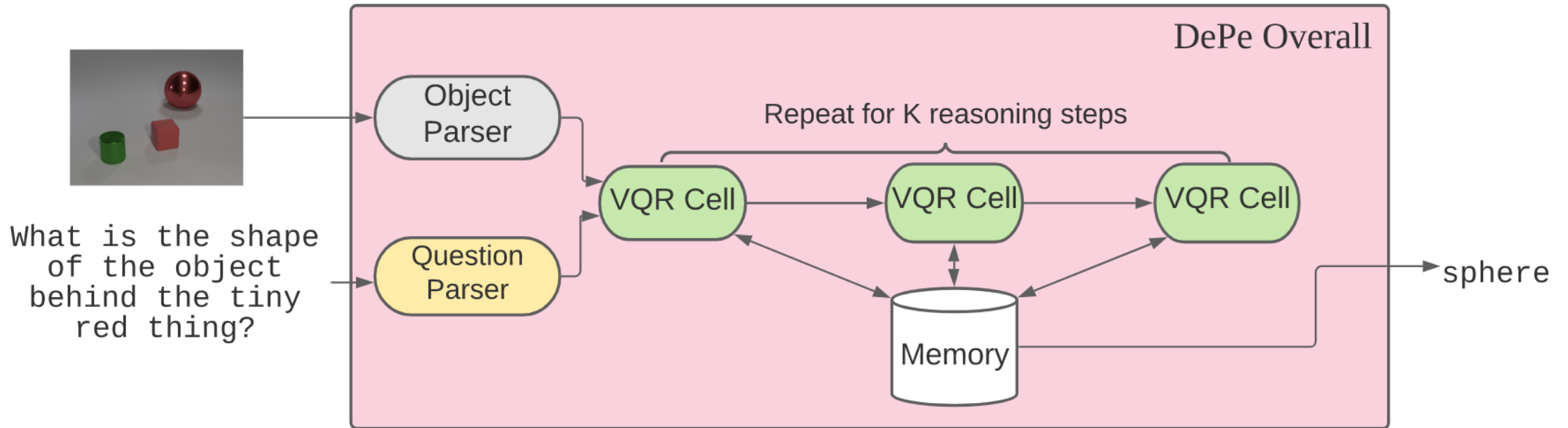
Why is this hard?

Exponential space of possible queries and solutions as the length grows.

Intuition: Compute the expected output conditioned on the current query function and the vision.



Differentiable End-to-End Program Executor (DePe)



The key is to design the memory can handle:

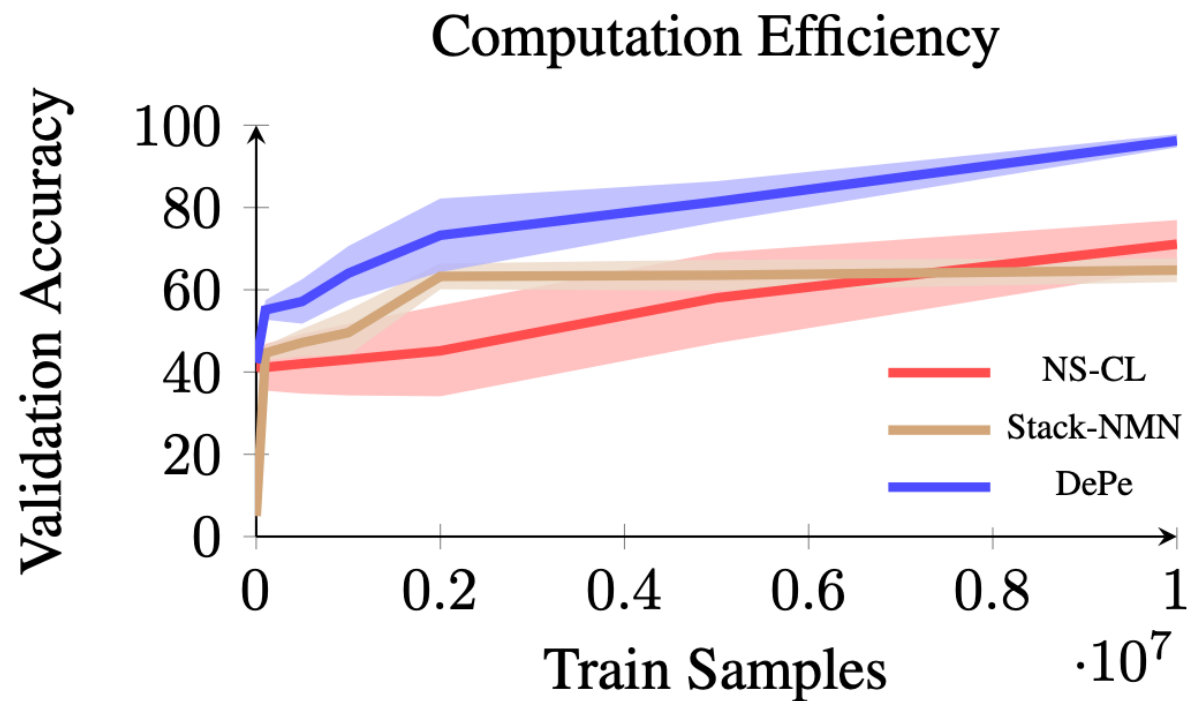
- **Symbolic representations**
- **Sub-queries**
- **Gradient computation throughout the entire execution**

DePe - Results

Results on CLEVR. Results on GQA in progress.

Sample Efficiency

QA Data %	Stack-NMN	NS-CL	DePe
1%	43.6	68.1	65.4
5%	66.6	86.7	87.7
10%	80.6	98.8	98.0



DePe – Future Work

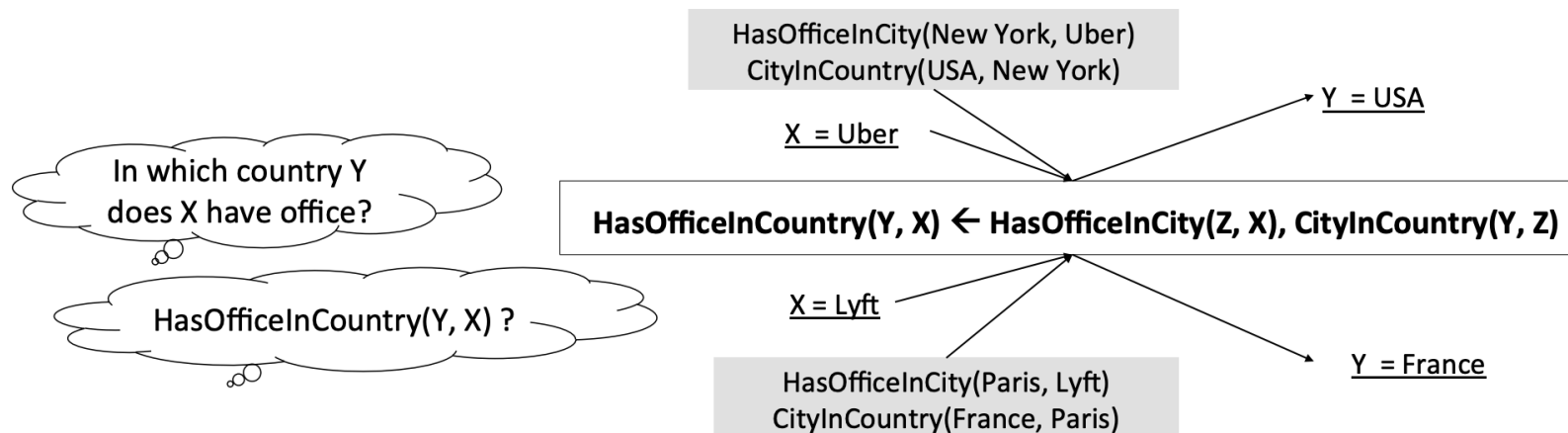
- **Does the DSL cover natural questions?**
- **Can we use entire image based features for non-object centric reasoning?**
- **Instead of image embeddings, or symbolic attributes can we store attribute embeddings in memory?**

Recovering logic rules from timeseries data

(Even more neural)

Background- Inductive Logic Programming

Given data on entities and their relations, can we derive new composite relations (rules)?



Given X can we walk along a knowledge graph to arrive at Y, and vice versa.

Background- Inductive Logic Programming

Given sparse representations of entities X, Y and relations R, determine which relations are required to arrive from X to Y

$$\mathbf{s} = \sum_l (\alpha_l (\prod_{\mathbf{k} \in \beta_l} \mathbf{M}_{R_{\mathbf{k}}} \mathbf{v}_{\mathbf{x}})) , \text{score}(\mathbf{y} | \mathbf{x}) = \mathbf{v}_{\mathbf{y}}^T \mathbf{s}$$

**Here we assume that that the entities, as well as their relations are provided.
Can we assume this in timeseries data?**

Problem Formulation – Time Series

- **Investigating timeseries inference where observed events induced by a compact subset of other events:**

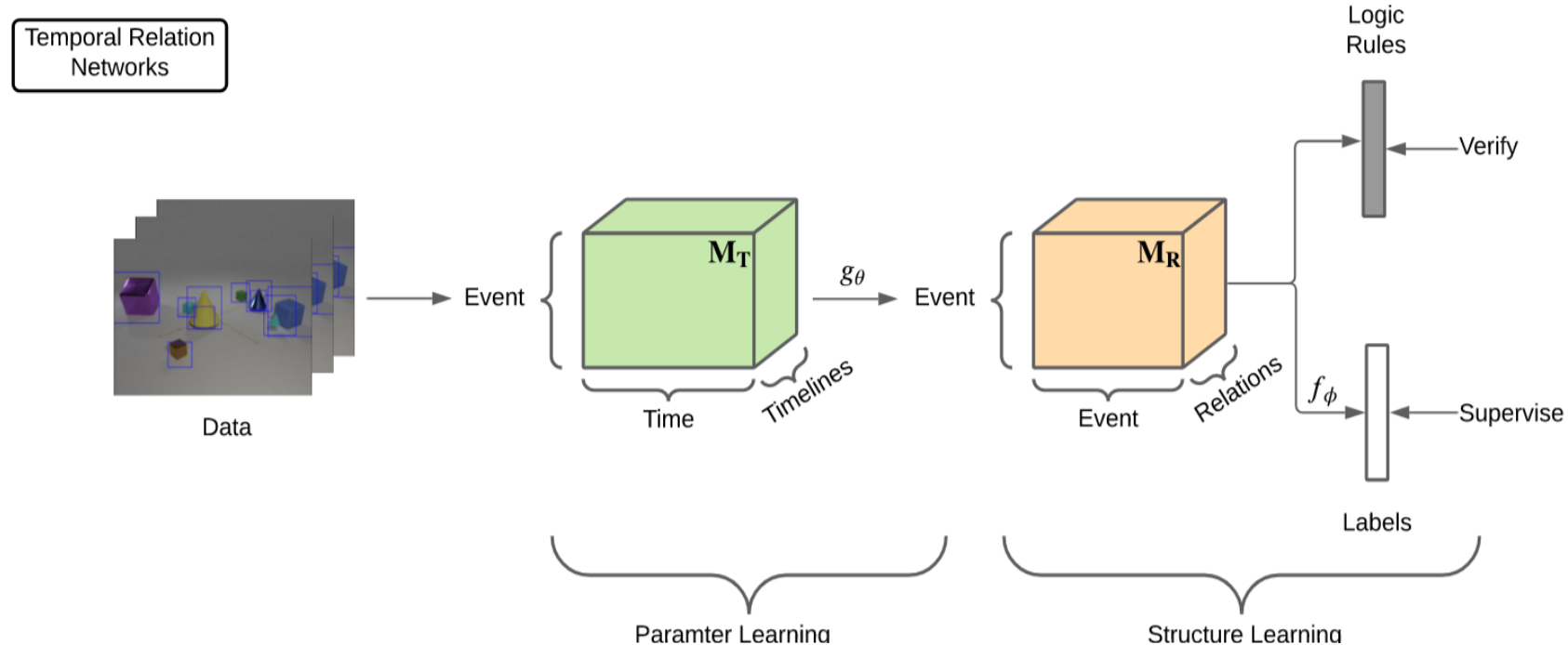
long jump := before(run, jump)

- **We may have labeled atomic event data, but rarely explicit relational data.**
- **Can we learn both the rule structure and the relation parameters for logic time series?**

High Level Framework

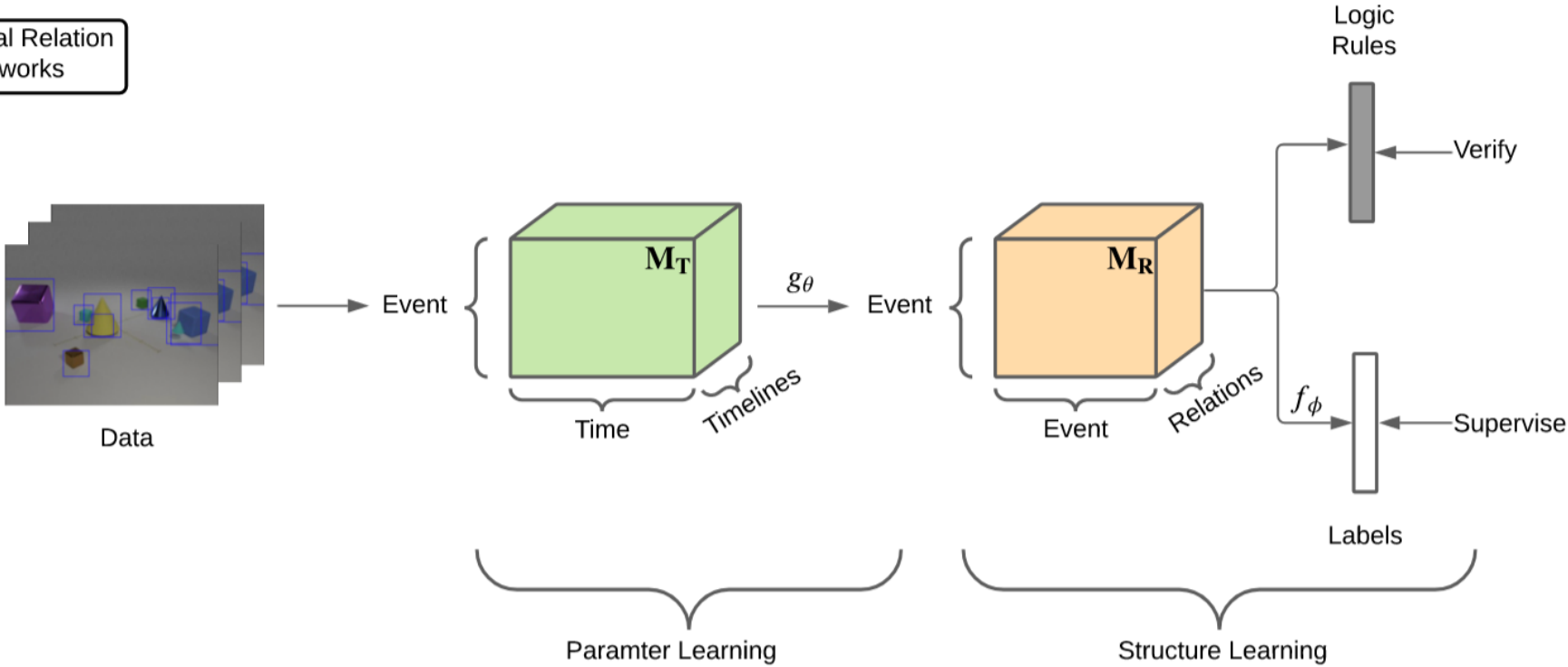
Can we implicitly leverage the temporal relations between events?:

- **Optimize relations and rule structure end-to-end.**
- **Extract the underlying temporal logic rules for verification or discovery.**

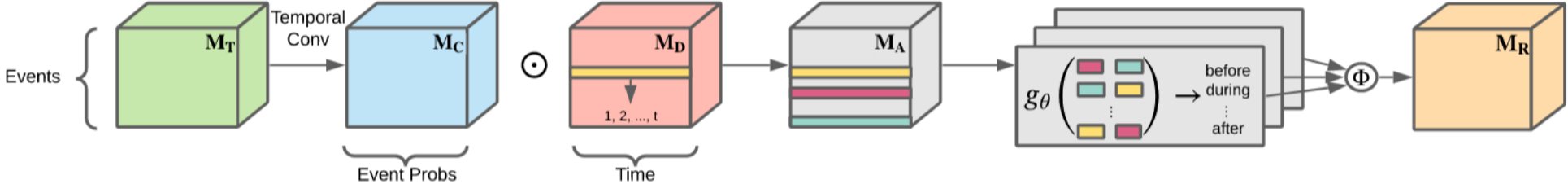


Temporal Relation Networks - Learning

Temporal Relation Networks

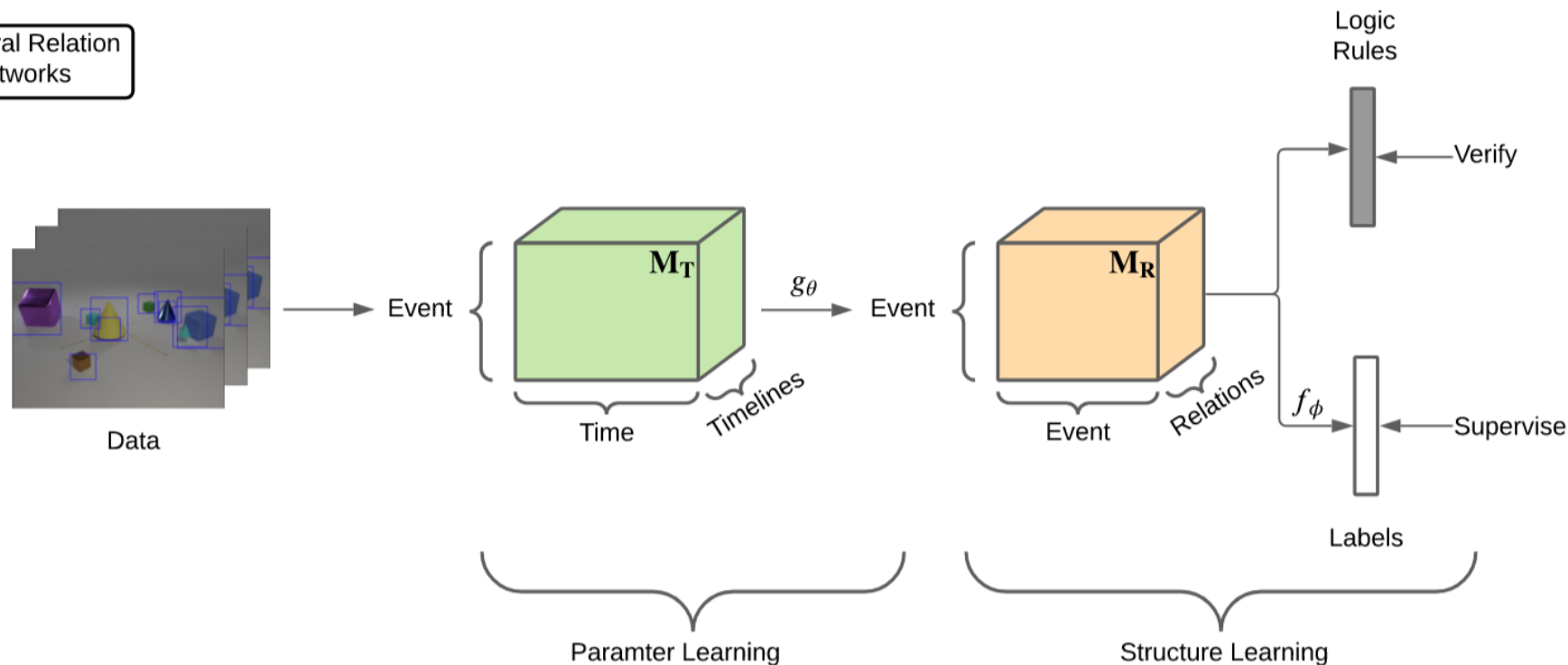


Parameter Learning



Temporal Relation Networks - Learning

Temporal Relation Networks

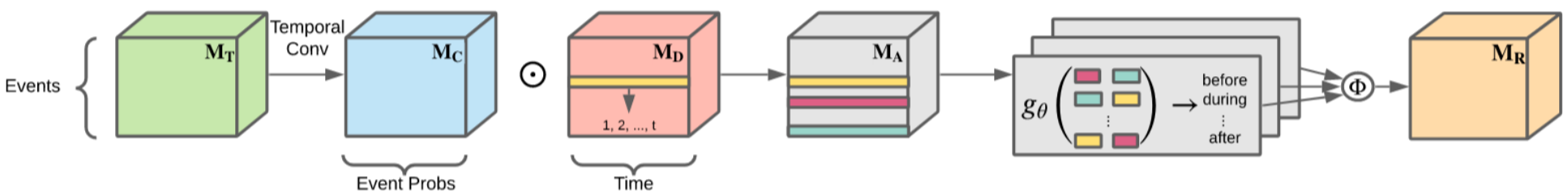


$$\arg \min_{\theta, \phi} - \sum_{(\hat{y}, y)} \sum_{i=1}^{|\mathbf{y}|} y_i \cdot \log(\hat{y}_i)$$

$$\text{s.t. } \min \|\mathbf{M}_R - \bar{\mathbf{M}}_R\|_F$$

$$\min \|\mathbf{M}_\alpha\|_1$$

Parameter Learning



Temporal Relation Networks - Extraction

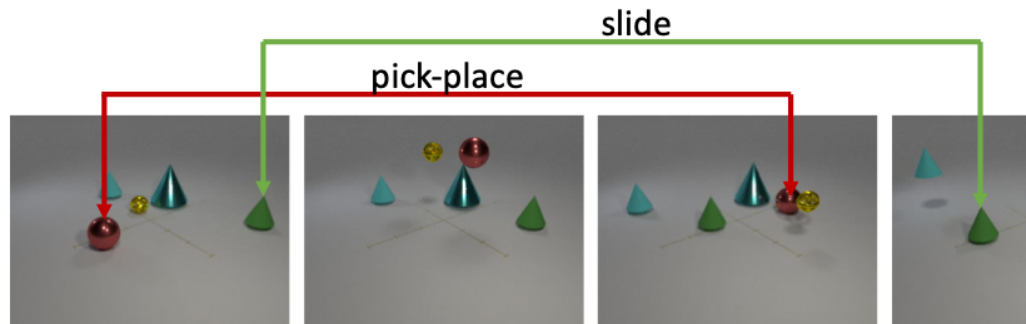
- **Given the weights of the structure model, we take the highest weighted fact triplets to generate the rules of length k .**

$$f(y_f) := \bigwedge_{i=1}^k r_t(x_u, x_v) ; P(f(y_f)) = \prod_{i=1}^k a_i^{y_f}$$

- **Variable length rules we can explore tree based methods.**

Current Work – Synthetic Verification

On synthetic data we can objectively evaluate our temporal rule extraction.



Event 5 :- during(pick-place, slide)

Robots wikiHow to do anything... Knowledge Base of Household Tasks

Action: Work on computer Description: Turn on your computer and sit in front of it. Type on the keyboard, grab the mouse to scroll.	Action: Make coffee Description: Go to the kitchen and swith on the coffee machine. Wait until it's done and pour the coffee into a cup.	Action: Read a book Description: Sit down in recliner. Pick up a novel off of coffee table. Open novel to last read page. Read.
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VirtualHome robot playground

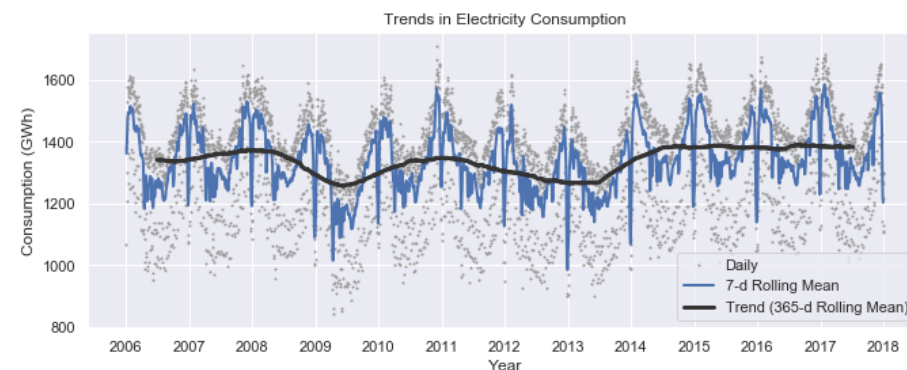
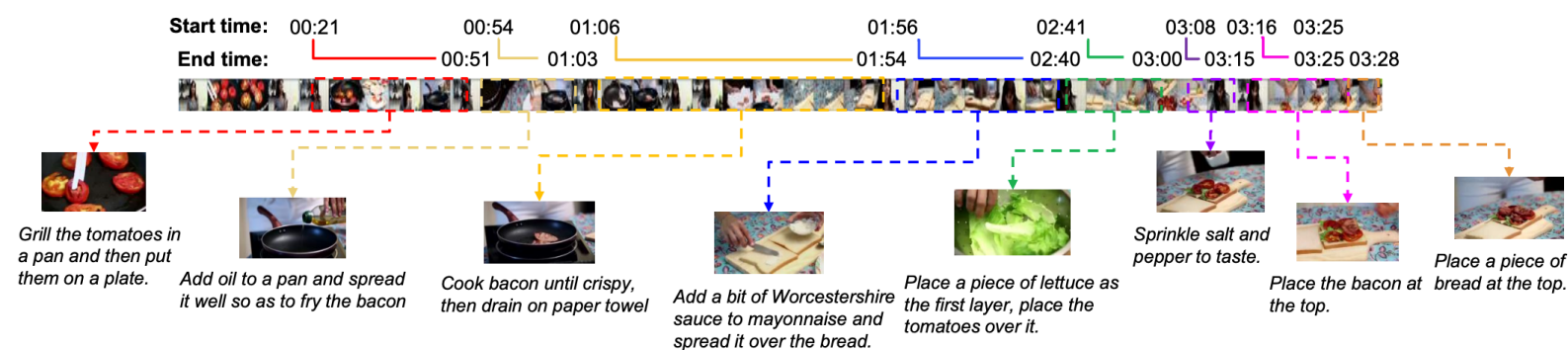
program

- action starts
- walk to Computer number 1
- switch on Computer number 1
- sit in Chair number 1
- touch Keyboard number 1
- touch Keyboard number 1
- grab Mouse number 1

video

Future Work – Proposed Datasets

On real world timeseries data we can subjectively evaluate our rule proposals.



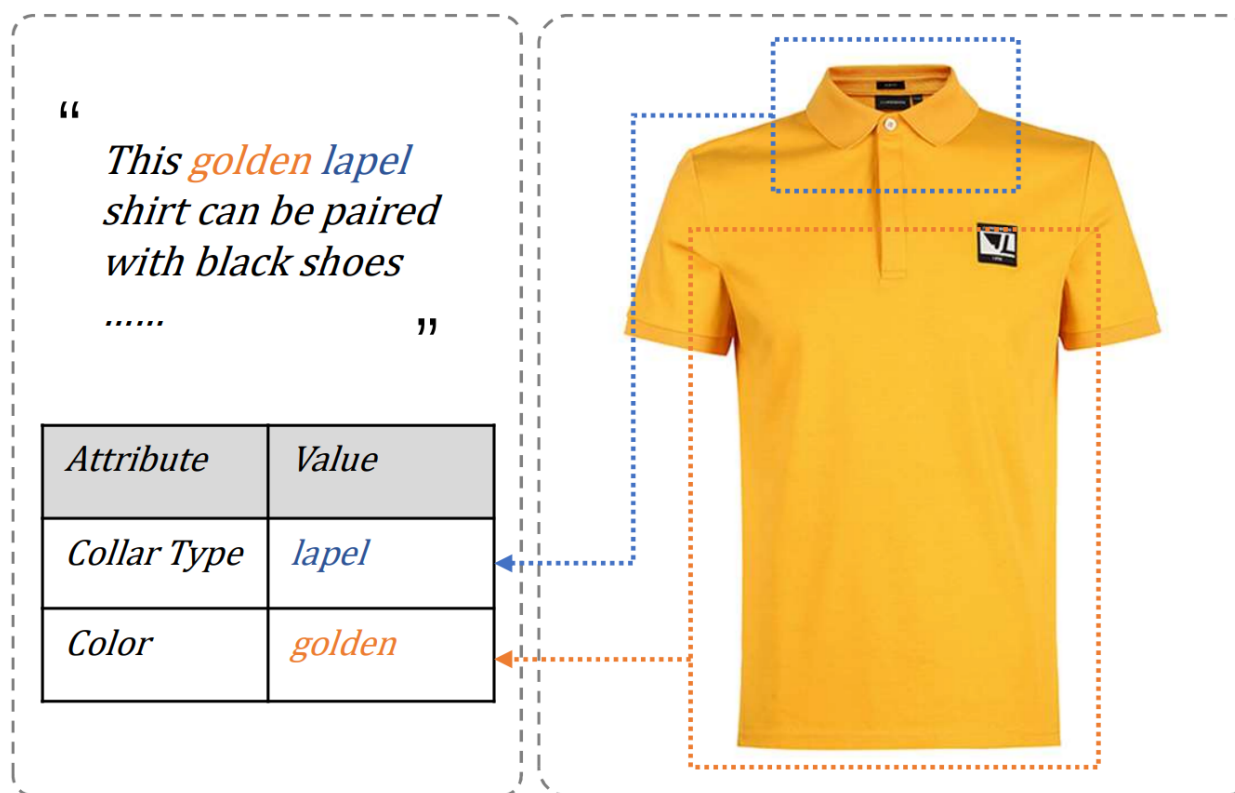
Future Directions

Multi-Modal Knowledge Construction

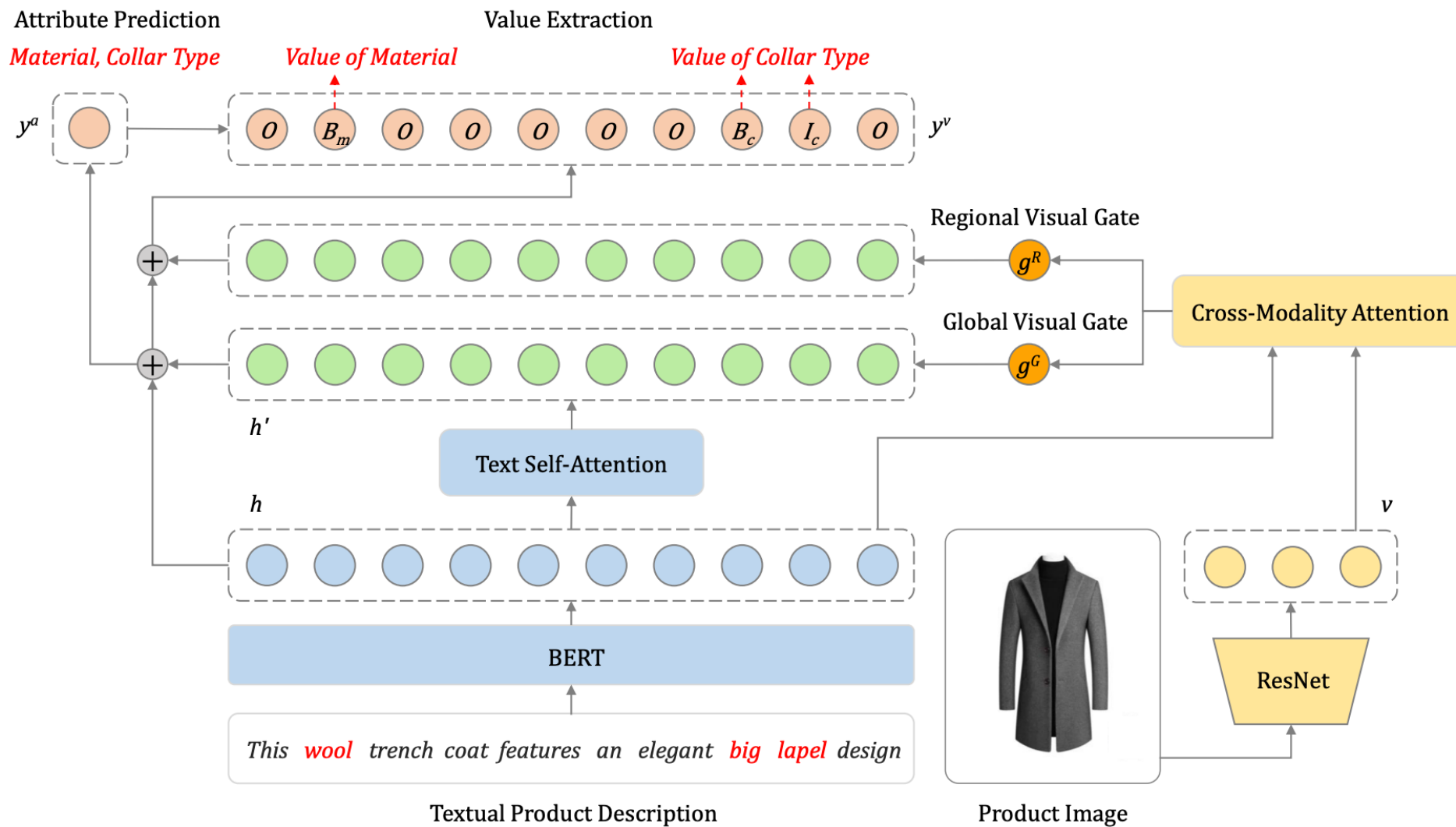
- **We leverage a small percentage of structured data for knowledge based methods**
- **Most recent works focus on construction based on single modalities, ie text.**
- **How do we leverage jointly leverage unstructured text, images, or videos to construct this knowledge?**

Multi-Modal Knowledge Construction

Fill in knowledge gaps in specific domains.



Multi-Modal Knowledge Construction



Constructed Knowledge for Real World Tasks

- **We have seen methods leveraging a DSL to reason over scene graphs and knowledge graphs.**
- **How effective are these functions given natural queries?**
- **Are there effective ways to determine a compact subset of these functions?**
- **Are there more effective methods besides just pure discrete reasoning vs neural reasoning (GNN)?**

Research Summary

Covered a range of works in the neuro-symbolic spectrum:

- **Image Question Answering**
 - **Real world symbolic execution and training**
 - **Handling uncertainty in symbolic learning**
- **Rule learning and inference over videos**
- **Future Directions**
 - **Multi-modal knowledge construction**
 - **Real world reasoning over inferred knowledge**

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